## **SIEMENS**

## **Data sheet**

## 6ES7677-2DB42-0GB0

SIMATIC ET 200SP Open Controller, CPU 1515SP PC2, 8 GB RAM, 128 GB CFast with Windows 10 IoT Enterprise 64-bit and S7-1500 Software Controller CPU 1505SP pre-installed, Interfaces: 1x Slot CFast, 1x slot SD/MMC, 1x connection for ET 200SP bus Adapter PROFINET, 1x 10/100/1000 Mbit/s Ethernet, 2x USB 3.0, 2x USB 2.0, 1x display port, Documentation on CFast Restore image on CFast



General information	
Product type designation	CPU 1515SP PC2
HW functional status	from FS04
Firmware version	V20.8
Engineering with	
<ul> <li>STEP 7 TIA Portal configurable/integrated from version</li> </ul>	V16
Installed software	
Visualization	No
Control	S7-1500 Software Controller CPU 1505SP
Configuration control	
via dataset	Yes
Control elements	
Mode selector switch	1
Supply voltage	
Type of supply voltage	24 V DC
permissible range, lower limit (DC)	19.2 V
permissible range, upper limit (DC)	28.8 V

Reverse polarity protection	Yes
Mains buffering	
Mains/voltage failure stored energy time	5 ms
· · · · · · · · · · · · · · · · · · ·	
nput current	40.4.5.11
Current consumption (rated value)	1.8 A; Full processor load, incl. ET 200SP modules and using USB
Current consumption (in no-load operation), typ.	0.5 A
Current consumption, max.	2.9 A
l <sup>2</sup> t	0.426 A <sup>2</sup> ·s; with starting current inrush
Power	
Active power input, max.	43 W; incl. ET 200SP modules and using USB
Infeed power to the backplane bus	8.75 W
Power loss	
Power loss, typ.	16 W
Processor	
Processor type	Intel Atom E3940, 1.6 GHz, 4 cores
Memory	
Type of memory	DDR3L
Main memory	8 GB RAM
CFast memory card	Yes; 128 GB flash memory
SIMATIC memory card required	No
Work memory	
• integrated (for program)	1 Mbyte
• integrated (for data)	5 Mbyte
• integrated (for CPU function library of CPU Runtime)	20 Mbyte
Load memory	
• integrated (on PC mass storage)	320 Mbyte
Backup	
• with UPS	Yes; all memory areas declared retentive
• with non-volatile memory	Yes
CPU processing times	
for bit operations, typ.	10 ns
for word operations, typ.	12 ns
for fixed point arithmetic, typ.	16 ns
for floating point arithmetic, typ.	64 ns
CPU-blocks	
	6 000; In addition to blocks such as DBs, FBs and FCs, UDTs,
Number of elements (total)	global constants, etc. are also regarded as elements

• Number, max.	5 999; Number range: 1 to 65535
• Size, max.	5 Mbyte
FB	
Number, max.	5 998; Number range: 1 to 65535
• Size, max.	1 024 kbyte
FC	
Number, max.	5 999; Number range: 1 to 65535
• Size, max.	1 024 kbyte
ОВ	
• Size, max.	1 024 kbyte
<ul> <li>Number of free cycle OBs</li> </ul>	100
<ul> <li>Number of time alarm OBs</li> </ul>	20
<ul> <li>Number of delay alarm OBs</li> </ul>	20
<ul> <li>Number of cyclic interrupt OBs</li> </ul>	20
<ul> <li>Number of process alarm OBs</li> </ul>	50
<ul> <li>Number of DPV1 alarm OBs</li> </ul>	3
<ul> <li>Number of isochronous mode OBs</li> </ul>	1
<ul> <li>Number of technology synchronous alarm OBs</li> </ul>	2
<ul> <li>Number of startup OBs</li> </ul>	100
<ul> <li>Number of asynchronous error OBs</li> </ul>	4
<ul> <li>Number of synchronous error OBs</li> </ul>	2
<ul> <li>Number of diagnostic alarm OBs</li> </ul>	1
Nesting depth	
• per priority class	24
Counters, timers and their retentivity	
S7 counter	
Number	2 048
Retentivity	
— adjustable	Yes
IEC counter	
Number	Any (only limited by the main memory)
Retentivity	
— adjustable	Yes
S7 times	
• Number	2 048
Retentivity	
— adjustable	Yes
IEC timer	
• Number	Any (only limited by the main memory)
Number     Retentivity	Any (only limited by the main memory)

Data areas and their retentivity	
Retentive data area (incl. timers, counters, flags),	410 kbyte; For storage in NVRAM; for storage in mass storage 5
max.	242 020 bytes
Flag	
Number, max.	16 kbyte
Number of clock memories	8; 8 clock memory bit, grouped into one clock memory byte
Data blocks	
Retentivity adjustable	Yes
Retentivity preset	No
Local data	
• per priority class, max.	64 kbyte; max. 16 KB per block
Address area	
Number of IO modules	8 192
I/O address area	
• Inputs	32 kbyte; All inputs are in the process image
<ul><li>Outputs</li></ul>	32 kbyte; All outputs are in the process image
Subprocess images	
<ul> <li>Number of subprocess images, max.</li> </ul>	32
Hardware configuration	
Integrated power supply	Yes
Number of distributed IO systems	20
Number of DP masters	
● Via CM	1
Number of IO Controllers	
• via PC interfaces	1
Rack	
<ul> <li>Modules per rack, max.</li> </ul>	64; CPU 1515SP PC + 64 modules + server module
<ul> <li>Number of lines, max.</li> </ul>	1
PtP CM	
Number of PtP CMs	the number of connectable PtP CMs is only limited by the number of available slots
Time of day	
Clock	
• Type	Hardware clock
Hardware clock (real-time)	Yes; Resolution: 1 s
Backup time	6 wk; At 40 °C ambient temperature, typically
Deviation per day, max.	10 s; Typ.: 2 s
Clock synchronization	
• supported	Yes
• to DP, master	Yes
• on Ethernet via NTP	Yes
OII EUROTICE VIOLENTI	

• on Windows clock, slave	Yes
Interfaces	
Number of industrial Ethernet interfaces	2
Number of PROFINET interfaces	1
Number of PROFIBUS interfaces	1
Number of RS 485 interfaces	1; Via CM DP module
Number of USB interfaces	4; 2x USB 2.0, 2x USB 3.0 on front side
Number of SD card slots	1
Video interfaces	
Graphics interface	1x DisplayPort
1. Interface	
Interface type	PROFINET
automatic detection of transmission rate	Yes
Autonegotiation	Yes
Autocrossing	Yes
Number of connections	88
Interface types	
<ul><li>Number of ports</li></ul>	2
• integrated switch	Yes
• RJ 45 (Ethernet)	Yes; Via BusAdapter BA 2x RJ45
— Transmission rate, max.	100 Mbit/s
<ul> <li>Industrial Ethernet status LED</li> </ul>	Yes
BusAdapter (PROFINET)	Yes; Compatible BusAdapter: BA 2x RJ45, BA 2x FC, BA 2x SCRJ (from FS03, V2.2), BA SCRJ / RJ45 (from FS03, V3.1), BA SCRJ / FC (from FS03, V3.1), BA 2x LC (from FS03, V3.3), BA LC / RJ45 (from FS03, V3.3), BA LC / FC (from FS03, V3.3)
Protocols	
PROFINET IO Controller	Yes
PROFINET IO Device	Yes
SIMATIC communication	Yes
Open IE communication	Yes
Web server	Yes
PROFINET IO Controller	
Services	
— Isochronous mode	Yes
— shortest clock pulse	500 μs
— IRT	Yes
— MRP	Yes
— MRPD	Yes
— PROFlenergy	Yes

— Prioritized startup	Yes; Max. 32 PROFINET devices; if you want to use the "Prioritized startup" functionality in STEP 7 for the PROFINET interface of the CPU, the CPU and the device must be separated by means of a switch (e.g. SCALANCE X205)
<ul> <li>Number of connectable IO Devices, max.</li> </ul>	128
<ul><li>Of which IO devices with IRT, max.</li></ul>	64
— of which in line, max.	64
<ul> <li>Number of connectable IO Devices for RT, max.</li> </ul>	128
— of which in line, max.	128
<ul> <li>Number of IO Devices that can be simultaneously activated/deactivated, max.</li> </ul>	8
<ul> <li>— IO Devices changing during operation (partner ports), supported</li> </ul>	Yes
<ul> <li>Number of IO Devices per tool, max.</li> </ul>	8
— Updating times	The minimum value of the update time also depends on communication share set for PROFINET IO, on the number of IO devices, and on the quantity of configured user data
Update time for IRT	
— for send cycle of 500 μs	500 μs to 8 ms
— for send cycle of 1 ms	1 ms to 16 ms
— for send cycle of 2 ms	2 ms to 32 ms
— for send cycle of 4 ms	4 ms to 64 ms
<ul> <li>With IRT and parameterization of "odd" send cycles</li> </ul>	Update time = set "odd" send clock (any multiple of 125 $\mu$ s: 375 $\mu$ s, 625 $\mu$ s 3 875 $\mu$ s)
Update time for RT	
— for send cycle of 500 μs	500 μs to 256 ms
— for send cycle of 1 ms	1 ms to 512 ms
— for send cycle of 2 ms	2 ms to 512 ms
— for send cycle of 4 ms	4 ms to 512 ms
Address area	
— Inputs, max.	8 kbyte
— Outputs, max.	8 kbyte
PROFINET IO Device	
Services	
— Isochronous mode	No
<ul><li>— shortest clock pulse</li></ul>	500 μs
— IRT	Yes
— MRP	Yes
— MRPD	Yes
— PROFlenergy	Yes
<ul> <li>Prioritized startup</li> </ul>	Yes
— Shared device	Yes

<ul> <li>Number of IO Controllers with shared device, max.</li> </ul>	4
Asset management record	Yes
2. Interface	
Interface type	Integrated Ethernet interface
automatic detection of transmission rate	Yes
Autonegotiation	Yes
Autocrossing	Yes
Interface types	
<ul><li>Number of ports</li></ul>	1
• RJ 45 (Ethernet)	Yes; Integrated
— Transmission rate, max.	1 000 Mbit/s
— Industrial Ethernet status LED	No
3. Interface	
Interface type	PROFIBUS with CM DP
Number of connections via this interface	44
Interface types	
• RS 485	Yes
Protocols	
PROFIBUS DP master	Yes
<ul> <li>PROFIBUS DP slave</li> </ul>	Yes
<ul> <li>SIMATIC communication</li> </ul>	Yes
PROFIBUS DP master	
Number of DP slaves, max.	125
Services	
— Equidistance	No
— Isochronous mode	No
Address area	
— Inputs, max.	8 kbyte
— Outputs, max.	8 kbyte
Interface types	
RS 485	
<ul><li>Transmission rate, max.</li></ul>	12 Mbit/s
Protocols	
Number of connections	
<ul><li>Number of connections, max.</li></ul>	88
<ul> <li>Number of connections reserved for ES/HMI/web</li> </ul>	10
_5/1 ///// 1/50	

Redundancy mode

Media redundancy

• Number of S7 routing paths

16

<ul> <li>Switchover time on line break, typ.</li> </ul>	200 ms
	50
Number of stations in the ring, max.  SIMATIC communication	30
PG/OP communication	Yes
• S7 routing	Yes
-	Yes
S7 communication, as server	Yes
S7 communication, as client	
User data per job, max.  Onen IF communication.	64 kbyte; BSEND/BRCV: 64 KB; PUT/GET: 960 bytes
Open IE communication	Yes
• TCP/IP	
— Data length, max.	64 kbyte
• ISO-on-TCP (RFC1006)	Yes
— Data length, max.	64 kbyte
• UDP	Yes
— Data length, max.	2 048 byte
• SNMP	Yes
• DCP	Yes
• LLDP	Yes
Web server	
• HTTP	Yes; Via Windows and PROFINET interface
• HTTPS	Yes; Via Windows and PROFINET interface
OPC UA	
<ul> <li>Runtime license required</li> </ul>	Yes; "Small" license required
OPC UA Client	Yes; From SW CPU 1505SP V2.6
OPC UA Server	Yes; Data access (read, write, subscribe), runtime license required
<ul> <li>Application authentication</li> </ul>	Yes; Available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256
<ul> <li>Security policies</li> </ul>	Yes; Available security policies: None, Basic128Rsa15,
	Basic256Rsa15, Basic256Sha256
<ul> <li>User authentication</li> </ul>	Yes; "anonymous" or by user name & password
Further protocols	
• MODBUS	Yes; MODBUS TCP
S7 message functions	
Number of login stations for message functions, max.	32
Program alarms	Yes
Number of configurable program messages, max.	10 000
Number of simultaneously active program alarms	1 000
Number of program alarms	1 000
Number of alarms for system diagnostics	200
<ul> <li>Number of alarms for motion technology objects</li> </ul>	160

Diagnostics indication LED  ◆ RUN/STOP LED  ◆ ERROR LED  ◆ MAINT LED  Yes  Yes	Test commissioning functions	
Single step No Number of breakpoints 8 Status/control variable • Ves • Variables Inputs, outputs, memory bits, DB, times, counters • Number of variables, max. — of which status variables, max. — of which control variables, max. 200 Forcing Ves • Forcing Yes • Forcing, variables, max. 200  Forcing variables Inputs, outputs • Number of variables, max. 200  Diagnostic buffer • present • Number of entries, max. — of which powerfall-proof 300  Traces • Number of configurable Traces 4 • Memory size per trace, max. 512 kbyte  Interrupts/diagnostics/status information  Diagnostics indication LED • RUN/STOP LED • REROR LED • MAINT LED • MAINT LED  Supported technology objects  Motion Control • Number of available Motion Control resources for technology objects  • Required Motion Control resources for per speed-controlled axis — per speed-controlled axis — per synchronous axis — per synchronous axis — per output cam — per camt tack — per probe  160; per cam  160; per camt rack — per probe	Joint commission (Team Engineering)	
Number of breakpoints  Status/control variable  • Status/control variables  • Variables  • Number of variables, max.  — of which status variables, max.  — of which control variables, max.  • Forcing  • Forcing  • Forcing  • Forcing, variables  • Number of variables, max.  200  Diagnostic buffer  • present  • Number of entries, max.  — of which powerfall-proof  • Number of configurable Traces  • Number of configurable Traces  • Memory size per trace, max.  1000  • RUNSTOP LED  • RRUNSTOP LED  • RROR LED  • MAINT LED  Supported technology objects  Motion Control  • Neuriber of available Motion Control resources for technology objects  • Required Motion Control resources  — per speed-controlled axis  — per positioning axis  — per synchronous axis  — per synchronous axis  — per synchronous axis  — per output cam  — per cam track  — per probe  40; per cam  — per cam track  — per probe  40; per cam  — per cam track  — per probe  40; per cam track  — per probe	Status block	Yes; up to 8 simultaneously
Status/control variable  Status/control variable  Variables Inputs, outputs, memory bits, DB, times, counters  Of which status variables, max.  Of which status variables, max.  Inputs, outputs  Inputs, outputs  Inputs, outputs  Inputs, outputs  Inputs, outputs  Inputs, outputs  Of variables  Inputs, outputs  Inputs,	Single step	No
Status/control variable  Variables  Inputs, outputs, memory bits, DB, times, counters  Outputs, outputs  Forcing  Forcing  Forcing  Forcing, variables, max.  Inputs, outputs  Inputs, memory bits, DB, times, counters  Inputs, outputs, memory bits, DB, times, counters  Inputs, outputs  Inputs, outputs  Inputs, memory bits, DB, times, counters  Inputs, outputs, memory bits, DB, times, counters  Inputs, outputs, memory bits, DB, times, outputs  Inputs, outputs, memory bits, DB, times, counters  Inputs, outputs, memory bits, DB, times, counters, outputs, outp	Number of breakpoints	8
Variables     Inputs, outputs, memory bits, DB, times, counters     Number of variables, max.     — of which status variables, max.     — of which control variables, max.     — of which control variables, max.      Forcing     Forcing     Forcing, variables     Inputs, outputs	Status/control	
Number of variables, max.  of which status variables, max.  of which control variables, max.  of which control variables, max.  200  Forcing  Forcing  Forcing, variables  Number of variables, max.  200  Diagnostic buffer  present  Number of entries, max.  of which powerfail-proof  Traces  Number of configurable Traces  Number of configurable Traces  Number of configurable Traces  Number of configurable Traces  Number of sonfigurable Traces  Number of sonfigura	Status/control variable	Yes
- of which status variables, max. 200  Forcing  Forcing  Forcing Yes Forcing, variables Forcing	<ul> <li>Variables</li> </ul>	Inputs, outputs, memory bits, DB, times, counters
Forcing  Forcing Forcing Forcing, variables Forcing	<ul> <li>Number of variables, max.</li> </ul>	
Forcing  Forcing Forcing, variables Forcing, variab	— of which status variables, max.	200
Forcing, variables Forcing, variables Number of variables, max.  Diagnostic buffer  Present Ves Number of entries, max. Of which powerfail-proof Traces  Number of configurable Traces Memory size per trace, max.  Interrupts/diagnostics/status information  Diagnostics indication LED  RUN/STOP LED REROR LED MAINT LED  Supported technology objects  Motion Control Required Motion Control resources for technology objects  Required Motion Control resources Per speed-controlled axis Per positioning axis Per external encoder Per output cam Per cam track Per por probe Per per per probe Per per per probe Per p	<ul><li>of which control variables, max.</li></ul>	200
Forcing, variables Number of variables, max.  Diagnostic buffer  present  present  Number of entries, max.  of which powerfail-proof  Number of configurable Traces  Number of side and the side of the s	Forcing	
Number of variables, max.  Diagnostic buffer  present  present  Number of entries, max.  of which powerfail-proof  Number of configurable Traces  Number of configurable Traces  Memory size per trace, max.  1000  Traces  Number of configurable Traces  Number of purpose trace, max.  Number of purpose trace, max.  Number of wall of the purpose trace, max.  Number of wall of the purpose trace, max.  Number of available Motion Control resources for technology objects  Required Motion Control resources  per speed-controlled axis  per per synchronous axis  per external encoder  per output cam  per cam track  per probe  Number of variables, max.  1000  Yes  2 400  Yes  2 400  Yes  3 400  Yes  400  Per axis  Notion per axis  Notion per axis  Notion per cam track  Per output cam  Per cam track  Per probe  Number of variables, max.  1000  1	• Forcing	Yes
Diagnostic buffer  • present • Number of entries, max. — of which powerfail-proof 300  Traces  • Number of configurable Traces • Memory size per trace, max.  Diagnostics/status information  Diagnostics indication LED  • RUN/STOP LED • RUN/STOP LED • MAINT LED  Supported technology objects  Motion Control • Number of available Motion Control resources for technology objects  • Required Motion Control resources — per speed-controlled axis — per positioning axis — per external encoder — per output cam — per cam track — per probe  1000  Yes  40; per axis  160; per cam track — per probe  40; per cam track — per probe	<ul><li>Forcing, variables</li></ul>	Inputs, outputs
present Number of entries, max. of which powerfail-proof  Number of configurable Traces  Number of configurable Traces Nemory size per trace, max.  Interrupts/diagnostics/status information  Diagnostics indication LED  RUN/STOP LED RUN/STOP LED RUN/STOP LED Nemory size per trace, max.  Notion Control Number of available Motion Control resources for technology objects  Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe  Number of examination  Yes  2 400  Number of available Motion Control resources for technology objects  Required Motion Control resources  A0; per axis  B0; per axis  B0; per external encoder  B0; per external encoder  Per output cam — per cam track — per probe  40; per probe	<ul> <li>Number of variables, max.</li> </ul>	200
Number of entries, max. — of which powerfail-proof  Traces  Number of configurable Traces Nemory size per trace, max.  Nemory size per trace, max.  Nemory size per trace, max.  S12 kbyte  Interrupts/diagnostics/status information  Diagnostics indication LED RUN/STOP LED REROR LED REROR LED MAINT LED Yes Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources Per speed-controlled axis Per per positioning axis Per external encoder Per external encoder Per output cam Per cam track Per probe  1000  10	Diagnostic buffer	
— of which powerfail-proof  Traces  • Number of configurable Traces • Memory size per trace, max.  Interrupts/diagnostics/status information  Diagnostics indication LED  • RUN/STOP LED • RUN/STOP LED • ERROR LED • MAINT LED  Supported technology objects  Motion Control  • Number of available Motion Control resources for technology objects  • Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe  • Number of available Motion Control resources  2 400  40; per axis  80; per axis  160; per cam  20; per cam  160; per cam track — per probe	• present	Yes
Traces  Number of configurable Traces Memory size per trace, max.  1512 kbyte  Interrupts/diagnostics/status information  Diagnostics indication LED RUN/STOP LED REROR LED MAINT LED  Supported technology objects  Motion Control Number of available Motion Control resources for technology objects  Required Motion Control resources Per speed-controlled axis Per per positioning axis Per external encoder Per output cam Per cam track Per probe  Number of available Motion Control resources Oper axis Per external encoder Per coutput cam Per cam track Per probe  40; per probe	<ul><li>Number of entries, max.</li></ul>	1 000
Number of configurable Traces  Memory size per trace, max.  Interrupts/diagnostics/status information  Diagnostics indication LED  RUN/STOP LED  ERROR LED  MAINT LED  Yes  Motion Control  Number of available Motion Control resources for technology objects  Required Motion Control resources  Per speed-controlled axis  per positioning axis  per synchronous axis  per external encoder  per output cam  per cam track  per probe  Number of configurable Traces  4  Yes  Yes  2 400  Yes  40; per axis  80; per axis  80; per axis  160; per axis  40; per cam track  Per cam track  Per cam track  Per probe	— of which powerfail-proof	300
Memory size per trace, max.  Interrupts/diagnostics/status information  Diagnostics indication LED  RUN/STOP LED ERROR LED MAINT LED  Supported technology objects  Motion Control Number of available Motion Control resources for technology objects  Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe  Memory size per trace, max.  1512 kbyte  Yes  Yes  2 400  400  400  400  400  400  400  4	Traces	
Interrupts/diagnostics/status information  Diagnostics indication LED  • RUN/STOP LED • ERROR LED • MAINT LED  Supported technology objects  Motion Control • Number of available Motion Control resources for technology objects • Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe  100; per cam track — per probe	Number of configurable Traces	4
Diagnostics indication LED         ● RUN/STOP LED       Yes         ● ERROR LED       Yes         ● MAINT LED       Yes         Supported technology objects         Motion Control       Yes         ● Number of available Motion Control resources for technology objects       2 400         ● Required Motion Control resources       — per speed-controlled axis       40; per axis         — per positioning axis       80; per axis         — per synchronous axis       160; per axis         — per external encoder       80; per external encoder         — per output cam       20; per cam         — per cam track       160; per cam track         — per probe       40; per probe	<ul> <li>Memory size per trace, max.</li> </ul>	512 kbyte
RUN/STOP LED  ERROR LED  MAINT LED  Supported technology objects  Motion Control  Number of available Motion Control resources for technology objects  Required Motion Control resources  Per speed-controlled axis  per positioning axis  per positioning axis  per synchronous axis  per external encoder  per output cam  per cam track  per probe  Yes  Yes  400  400  400  401  402  405  405  407  407  407  407  407  408  FREQUIRED  Yes  AUC  400  400  400  400  400  400  400  4	Interrupts/diagnostics/status information	
ERROR LED     Yes     MAINT LED  Supported technology objects  Motion Control     Number of available Motion Control resources for technology objects  Required Motion Control resources     Per speed-controlled axis     Per positioning axis     Per prositioning axis     Per external encoder     Per output cam     Per cam track     Per probe  Yes  2 400  40; per axis  40; per axis  80; per axis  160; per axis  20; per cam  160; per cam track  160; per cam track  40; per probe		
● MAINT LED  Yes  Supported technology objects  Motion Control  ● Number of available Motion Control resources for technology objects  ● Required Motion Control resources  — per speed-controlled axis  — per positioning axis  — per synchronous axis  — per external encoder  — per output cam  — per cam track  — per probe  Yes  2 400  40; per axis  40; per axis  80; per axis  160; per axis  160; per cam  160; per cam  160; per cam  40; per probe	RUN/STOP LED	
Supported technology objects  Motion Control  Number of available Motion Control resources for technology objects  Required Motion Control resources  per speed-controlled axis  per positioning axis  per synchronous axis  per external encoder  per output cam  per cam track  per probe  Yes  2 400  40; per axis  40; per axis  80; per axis  80; per axis  160; per axis  160; per cam  160; per cam  160; per cam track  40; per probe	• ERROR LED	
Motion Control       Yes         ● Number of available Motion Control resources for technology objects       2 400         ● Required Motion Control resources       — per speed-controlled axis         — per positioning axis       40; per axis         — per positioning axis       80; per axis         — per synchronous axis       160; per axis         — per external encoder       80; per external encoder         — per output cam       20; per cam         — per cam track       160; per cam track         — per probe       40; per probe	MAINT LED	Yes
<ul> <li>Number of available Motion Control resources for technology objects</li> <li>Required Motion Control resources</li> <li>— per speed-controlled axis</li> <li>— per positioning axis</li> <li>— per synchronous axis</li> <li>— per external encoder</li> <li>— per output cam</li> <li>— per cam track</li> <li>— per probe</li> <li>2 400</li> <li>40; per axis</li> <li>80; per axis</li> <li>80; per external encoder</li> <li>20; per cam</li> <li>40; per cam track</li> <li>40; per probe</li> </ul>	Supported technology objects	
for technology objects  • Required Motion Control resources  — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe  40; per axis  80; per axis  80; per external encoder  20; per cam  160; per cam track 40; per probe	Motion Control	Yes
<ul> <li>per speed-controlled axis</li> <li>per positioning axis</li> <li>per synchronous axis</li> <li>per external encoder</li> <li>per output cam</li> <li>per cam track</li> <li>per probe</li> <li>40; per axis</li> <li>80; per axis</li> <li>80; per external encoder</li> <li>20; per cam</li> <li>40; per cam track</li> <li>40; per probe</li> </ul>		2 400
<ul> <li>per positioning axis</li> <li>per synchronous axis</li> <li>per external encoder</li> <li>per output cam</li> <li>per cam track</li> <li>per probe</li> <li>80; per axis</li> <li>80; per axis</li> <li>80; per external encoder</li> <li>20; per cam</li> <li>160; per cam track</li> <li>40; per probe</li> </ul>	<ul> <li>Required Motion Control resources</li> </ul>	
<ul> <li>per synchronous axis</li> <li>per external encoder</li> <li>per output cam</li> <li>per cam track</li> <li>per probe</li> <li>160; per axis</li> <li>80; per external encoder</li> <li>20; per cam</li> <li>40; per probe</li> </ul>	— per speed-controlled axis	40; per axis
<ul> <li>per external encoder</li> <li>per output cam</li> <li>per cam</li> <li>per cam track</li> <li>per probe</li> <li>80; per external encoder</li> <li>20; per cam</li> <li>160; per cam track</li> <li>40; per probe</li> </ul>	— per positioning axis	80; per axis
<ul> <li>per output cam</li> <li>per cam</li> <li>per cam track</li> <li>per probe</li> <li>20; per cam</li> <li>160; per cam track</li> <li>40; per probe</li> </ul>	— per synchronous axis	160; per axis
— per cam track  — per probe  160; per cam track  40; per probe	— per external encoder	80; per external encoder
— per probe 40; per probe	— per output cam	20; per cam
	— per cam track	160; per cam track
Positioning axis	— per probe	40; per probe
	Positioning axis	

<ul> <li>Number of positioning axes at motion control cycle of 4 ms (typical value)</li> </ul>	15
Number of positioning axes at motion control cycle of 8 ms (typical value)	30
Controller	
PID_Compact	Yes; Universal PID controller with integrated optimization
PID_3Step	Yes; PID controller with integrated optimization for valves
● PID-Temp	Yes; PID controller with integrated optimization for temperature
Counting and measuring	
High-speed counter	Yes
Standards, approvals, certificates	
CE mark	Yes
CSA approval	Yes
cULus	Yes
FM approval	Yes
RCM (formerly C-TICK)	Yes
Ambient conditions	
Ambient temperature during operation	
• min.	-20 °C
• max.	Up to 60 °C with max. 32 ET 200SP modules; up to 55 °C with max. 64 ET 200SP modules
<ul> <li>horizontal installation, min.</li> </ul>	-20 °C
<ul> <li>horizontal installation, max.</li> </ul>	60 °C
• vertical installation, min.	-20 °C
• vertical installation, max.	50 °C; With max. 32 ET 200SP modules
Ambient temperature during storage/transportation	
• min.	-40 °C
• max.	70 °C
Vibrations	
Operation, tested according to IEC 60068-2-6	Yes
Transport, tested acc. to IEC 60068-2-6	Yes
Shock testing	
• tested according to IEC 60068-2-6	Yes
• tested according to IEC 60068-2-27	Yes
• tested according to IEC 60068-2-29	Yes
• Storage/transport, tested acc. to IEC 60068-2-27	Yes
Operating systems	
pre-installed operating system	Windows 10 IoT Enterprise 2016 LTSB, 64bit, MUI
Configuration	
Programming	

Programming language	
— LAD	Yes
— FBD	Yes
— STL	Yes
— SCL	Yes
— CFC	No
— GRAPH	Yes
Know-how protection	
User program protection/password protection	Yes
<ul> <li>Copy protection</li> </ul>	Yes
Block protection	Yes
Access protection	
Protection level: Write protection	Yes
<ul> <li>Protection level: Read/write protection</li> </ul>	Yes
<ul> <li>Protection level: Complete protection</li> </ul>	Yes
Cycle time monitoring	
• lower limit	adjustable minimum cycle time
• upper limit	adjustable maximum cycle time
Open Development interfaces	
• Size of ODK SO file, max.	5.8 Mbyte
Peripherals/Options	
SD card	Optionally for additional mass storage
Dimensions	
Width	160 mm
Height	117 mm
Depth	75 mm
Weights	
Weight, approx.	0.83 kg
last modified:	06/22/2020